

Θεμα 1 Καμπύλες

$$dx = -R\omega \sin \omega \lambda$$

$$dy = R\omega \cos \omega \lambda$$

$$dz = 0$$

$$dt = v d\lambda$$

$$ds^2 = (-v^2 + \omega^2 R^2) d\lambda^2$$

$$ds^2 < 0 \Leftrightarrow \omega R < v$$

$$|ds| = (-v^2 + \omega^2 R^2)^{1/2} d\lambda$$

$$\int_0^1 |ds| = (-v^2 + \omega^2 R^2)^{1/2} \lambda$$

$$d\tau^2 = (v^2 - \omega^2 R^2) d\lambda^2 \Rightarrow \tau = (v^2 - \omega^2 R^2)^{1/2} \lambda$$

$\tau(0) = 0$

Οπότε οι παραμ. εξισώσεις της καμπύλης γίνονται:

$$x(\tau) = R \cos \frac{\omega \tau}{\sqrt{v^2 - \omega^2 R^2}}$$

$$z(\tau) = 0$$

$$y(\tau) = R \sin \frac{\omega \tau}{\sqrt{v^2 - \omega^2 R^2}}$$

$$t(\tau) = \frac{v \tau}{\sqrt{v^2 - \omega^2 R^2}}$$

$$v^{\mu}(\lambda) = \frac{dx^{\mu}(\lambda)}{d\lambda} = (v, -\omega R \sin \omega \lambda, \omega R \cos \omega \lambda, 0)$$

$$w^{\mu}(\tau) = \frac{dx^{\mu}(\tau)}{d\tau} = \left(\frac{v}{\sqrt{v^2 - \omega^2 R^2}}, -\frac{\omega R}{\sqrt{v^2 - \omega^2 R^2}} \cos \frac{\omega \tau}{\sqrt{v^2 - \omega^2 R^2}}, \frac{\omega R}{\sqrt{v^2 - \omega^2 R^2}} \sin \frac{\omega \tau}{\sqrt{v^2 - \omega^2 R^2}}, 0 \right)$$

$$\underline{\Theta \in \mathcal{M}^2} \quad H/M \quad \Pi \in \mathcal{S}_{10} \quad G_{\mu\nu} \quad E \in \Sigma$$

$$F_{i0} = E_i \quad F_{ij} = \epsilon_{ijk} B_k$$

$$F_{10} = -F_{01} = -F^{10} = F^{01} = E_1$$

$$F_{20} = -F_{02} = -F^{20} = F^{02} = E_2$$

$$F_{30} = -F_{03} = -F^{30} = F^{03} = E_3$$

$$F_{12} = -F_{21} = F^{12} = -F^{21} = \epsilon_{123} B_3 = B_3$$

$$F_{13} = -F_{31} = F^{13} = -F^{31} = \epsilon_{132} B_2 = -B_2$$

$$F_{23} = -F_{32} = F^{23} = -F^{32} = \epsilon_{231} B_1 = B_1$$

$$\tilde{F}_{01} = \frac{1}{2} \epsilon_{0123} (F^{23} - F^{32}) = F^{23} = B_1$$

$$\tilde{F}_{02} = \frac{1}{2} \epsilon_{0213} (F^{13} - F^{31}) = -\epsilon_{0123} F^{13} = B_2$$

$$\tilde{F}_{03} = \frac{1}{2} \epsilon_{0312} (F^{12} - F^{21}) = \epsilon_{0123} F^{12} = B_3$$

$$\tilde{F}_{12} = \frac{1}{2} \epsilon_{1203} (F^{03} - F^{30}) = \epsilon_{0123} F^{03} = E_3$$

$$\tilde{F}_{13} = \frac{1}{2} \epsilon_{1302} (F^{02} - F^{20}) = -\epsilon_{0123} F^{02} = -E_2$$

$$\tilde{F}_{23} = \frac{1}{2} \epsilon_{2301} (F^{01} - F^{10}) = \epsilon_{0123} F^{01} = E_1$$

$$\Rightarrow \begin{cases} \tilde{F}_{0i} = B_i \\ \tilde{F}_{ij} = \epsilon_{ijk} E_k \end{cases}$$

$$F_{\mu\nu} F^{\mu\nu} = 2 F_{0i} F^{0i} + F_{ij} F^{ij} = -2 F_{0i}^2 + \tilde{F}_{ij}^2$$

$$= -2 E_i^2 + \epsilon_{ijk} B_k \epsilon_{ijl} B_l$$

$$= -2 E_i^2 + (\delta_{ii} \delta_{jj} - \delta_{ij} \delta_{ji}) B_k B_k$$

$$= -2 E_i^2 + 3 B_i^2 - B_i^2 = 2(-E_i^2 + B_i^2)$$

$$F_{\mu\nu} \tilde{F}^{\mu\nu} = -2 F_{0i} \tilde{F}^{0i} + F_{ij} \tilde{F}^{ij} =$$

$$= -2 (-E_i)(+B_i) + \epsilon_{ijk} B_k \epsilon_{ijl} E_l =$$

$$= 2 E_i B_i + 3 E_i B_i - E_i B_i = 4 E_i B_i$$

$$\tilde{F}_{\mu\nu} \tilde{F}^{\mu\nu} = -2 \tilde{F}_{0i} \tilde{F}^{0i} + \tilde{F}_{ij} \tilde{F}^{ij}$$

$$= -2 B_i^2 + \epsilon_{ijk} E_k \epsilon_{ijl} E_l = 2(-B_i^2 + E_i^2)$$

$$= -F_{\mu\nu} F^{\mu\nu}$$

ΘΕΜΑ 3 Το σύνηαν του Gödel

$$\left. \begin{aligned} t(z) &= 0 \\ r(z) &= R \\ \phi(z) &= \omega z \\ z(z) &= 0 \end{aligned} \right\} \Rightarrow \begin{aligned} u^t &= \dot{t} = 0 \\ u^r &= \dot{r} = 0 \\ u^\phi &= \dot{\phi} = \omega \\ u^z &= \dot{z} = 0 \end{aligned}$$

$$\begin{aligned} u_\mu u^\mu &= -(\cancel{u^t})^2 - 2 \frac{r^2}{\sqrt{2} a} \cancel{u^t} u^\phi + \frac{(\cancel{u^r})^2}{1 + (\frac{r}{za})^2} + r^2 \left[1 - \left(\frac{r}{za} \right)^2 \right] (\cancel{u^\phi})^2 + (\cancel{u^z})^2 \\ &= r^2 \left[1 - \left(\frac{r}{za} \right)^2 \right] \omega^2 = -r^2 \left[\left(\frac{r}{za} \right)^2 - 1 \right] \omega^2 < 0 \quad (r > z_a) \end{aligned}$$

Χρονοβίβος

Η 4-επιτάχυνση είναι:

$$\begin{aligned} a^\mu &= \ddot{x}^\mu + \Gamma^\mu_{\rho\sigma} \dot{x}^\rho \dot{x}^\sigma \\ &= 0 + \Gamma^\mu_{\phi\phi} \dot{\phi} \dot{\phi} \quad \left(\begin{array}{l} \text{όλα τα } \ddot{x}^\mu = 0 \\ \text{μόνο } u^\phi \neq 0 \end{array} \right) \end{aligned}$$

$$\text{μόνο } \Gamma^\rho_{\phi\phi} = r \left[1 + \left(\frac{r}{za} \right)^2 \right] \left[2 \left(\frac{r}{za} \right)^2 - 1 \right] \neq 0$$

$$\Rightarrow a^r \neq 0 \Rightarrow (\text{όχι γεωδαισική})$$

Οι συνιστώσες $g_{\mu\nu}$ δεν εξαρτώνται από ϕ

$$\Rightarrow \mathcal{L}_Z = \partial_\phi \quad \text{KV F}$$

$$k_2 = (\partial_\mu)^{\mu} u_\mu = g_{\mu\nu} (\partial_\mu)^{\mu} u^\nu$$

$$= g_{\phi t} (\partial_\mu)^{\mu} u^t + g_{\phi\phi} (\partial_\mu)^{\mu} u^\phi$$

$$= -\frac{r^2}{\sqrt{2}a} \dot{t} + r^2 \left[1 - \left(\frac{r}{2a} \right)^2 \right] \dot{\phi}$$

ΘΕΜΑ 4

$$\text{Έχουμε } \hat{e}_\mu = |g_{\mu\mu}|^{-1/2} \partial_\mu \Rightarrow v^{\hat{\mu}} = |g_{\mu\mu}|^{1/2} v^\mu$$
$$\omega_{\hat{\mu}} = |g_{\mu\mu}|^{-1/2} \omega_\mu$$

$$R^{\hat{\mu}\hat{\nu}\hat{\rho}\hat{\lambda}} = |g_{\mu\mu}|^{-1/2} |g_{\nu\nu}|^{-1/2} |g_{\rho\rho}|^{-1/2} |g_{\lambda\lambda}|^{-1/2} R_{\mu\nu\rho\lambda}$$

$$R^{\hat{r}\hat{t}\hat{r}\hat{t}} = |g_{tt}|^{-1} |g_{rr}|^{-1} R_{ttrt} = \left|1 - \frac{2M}{r}\right|^{-1} \left|1 - \frac{2M}{r}\right| \left(-\frac{2M}{r^3}\right)$$
$$= -\frac{2M}{r^3}$$

$$R^{\hat{\theta}\hat{t}\hat{\theta}\hat{t}} = |g_{tt}|^{-1} |g_{\theta\theta}|^{-1} R_{t\theta t\theta} = \left|1 - \frac{2M}{r}\right|^{-1} (r^2)^{-1} \frac{M}{r} \left(1 - \frac{2M}{r}\right)$$
$$= \frac{M}{r^3}$$

$$R^{\hat{\theta}\hat{\phi}\hat{\theta}\hat{\phi}} = |g_{\theta\theta}|^{-1} |g_{\phi\phi}|^{-1} R_{\theta\phi\theta\phi} = r^{-2} r^{-2} \sin^2\theta \, 2Mr \sin^2\theta$$
$$= \frac{2M}{r^3}$$

$$R^{\hat{\phi}\hat{t}\hat{\phi}\hat{t}} = |g_{tt}|^{-1} |g_{\phi\phi}|^{-1} R_{t\phi t\phi} = \left|1 - \frac{2M}{r}\right|^{-1} r^{-2} \sin^2\theta \, \frac{M}{r} \left(1 - \frac{2M}{r}\right) \sin^2\theta$$
$$= \frac{M}{r^3}$$

$$\begin{aligned}
 R_{\hat{r}\hat{\theta}\hat{r}\hat{\theta}} &= |g_{rr}|^{-1} |g_{\theta\theta}|^{-1} R_{r\theta r\theta} \\
 &= \left(1 - \frac{2M}{r}\right) r^{-2} \left[-\frac{M}{r} \left(1 - \frac{2M}{r}\right)^{-1}\right] \\
 &= -\frac{M}{r^3}
 \end{aligned}$$

$$\begin{aligned}
 R_{\hat{r}\hat{\phi}\hat{r}\hat{\phi}} &= |g_{rr}|^{-1} |g_{\phi\phi}|^{-1} R_{r\phi r\phi} \\
 &= \left(1 - \frac{2M}{r}\right) r^{-2} \sin^2\theta \left[-\frac{M}{r} \left(1 - \frac{2M}{r}\right)^{-1} \sin^2\theta\right] \\
 &= -\frac{M}{r^3}
 \end{aligned}$$

$$\begin{aligned}
 R_{\hat{0}\hat{1}\hat{0}\hat{1}} &= R_{\hat{t}\hat{r}\hat{t}\hat{r}} = -\frac{2M}{r^3} \\
 R_{\hat{0}\hat{2}\hat{0}\hat{2}} &= R_{\hat{t}\hat{\theta}\hat{t}\hat{\theta}} = \frac{M}{r^3} \\
 R_{\hat{2}\hat{3}\hat{2}\hat{3}} &= R_{\hat{\theta}\hat{\phi}\hat{\theta}\hat{\phi}} = \frac{2M}{r^3} \\
 R_{\hat{0}\hat{3}\hat{0}\hat{3}} &= R_{\hat{t}\hat{\phi}\hat{t}\hat{\phi}} = \frac{M}{r^3} \\
 R_{\hat{1}\hat{2}\hat{1}\hat{2}} &= R_{\hat{r}\hat{\theta}\hat{r}\hat{\theta}} = -\frac{M}{r^3} \\
 R_{\hat{1}\hat{3}\hat{1}\hat{3}} &= R_{\hat{r}\hat{\phi}\hat{r}\hat{\phi}} = -\frac{M}{r^3}
 \end{aligned}$$

Ex. 7. Fewer. annotations

$$\hat{u} = (1, 0, 0, 0)$$

$$\begin{aligned} \frac{D^2 \hat{\zeta}^\mu}{dz^2} &= R^{\hat{\mu}}_{\hat{\nu} \hat{\sigma}} \hat{u}^\nu \hat{u}^\sigma \hat{\zeta}^\mu \\ &\quad \hookrightarrow \text{now } u^t = 1 \neq 0 \\ &= R^{\hat{\mu}}_{\hat{t} \hat{\sigma}} \hat{\zeta}^\sigma = -R^{\hat{\mu}}_{\hat{t} \hat{\sigma} \hat{t}} \hat{\zeta}^\sigma \end{aligned}$$

$$\frac{D^2 \hat{\zeta}^0}{dz^2} = -R^{\hat{t}}_{\hat{t} \hat{\sigma} \hat{t}} \hat{\zeta}^\sigma = 0$$

$$\frac{D^2 \hat{\zeta}^{\hat{r}}}{dz^2} = -R^{\hat{r}}_{\hat{t} \hat{r} \hat{t}} \hat{\zeta}^{\hat{r}} = \frac{2M}{r^3} \hat{\zeta}^{\hat{r}}$$

$$\frac{D^2 \hat{\zeta}^{\hat{\theta}}}{dz^2} = -R^{\hat{\theta}}_{\hat{t} \hat{\theta} \hat{t}} \hat{\zeta}^{\hat{\theta}} = -\frac{M}{r^3} \hat{\zeta}^{\hat{\theta}}$$

$$\frac{D^2 \hat{\zeta}^{\hat{\phi}}}{dz^2} = -R^{\hat{\phi}}_{\hat{t} \hat{\phi} \hat{t}} \hat{\zeta}^{\hat{\phi}} = -\frac{M}{r^3} \hat{\zeta}^{\hat{\phi}}$$